

# Micro800 Programming Basics

## Tutorial 3: User Defined Function Block



***For Classroom Use Only!***

LISTEN.  
THINK.  
SOLVE.®

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Throughout this manual we use the following notes to make you aware of safety considerations:

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**WARNING**

Identifies information about practices or circumstances that can cause an explosion in a hazardous environment, which may lead to personal injury or death, property damage, or economic loss.

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**IMPORTANT**

Identifies information that is critical for successful application and understanding of the product.

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**ATTENTION**

Identifies information about practices or circumstances that can lead to personal injury or death, property damage, or economic loss. Attentions help you:

- identify a hazard
- avoid a hazard
- recognize the consequence

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**SHOCK HAZARD**

Labels may be located on or inside the drive to alert people that dangerous voltage may be present.

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**BURN HAZARD**

Labels may be located on or inside the drive to alert people that surfaces may be dangerous temperature

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## **About this lab**

Connected Components Workbench (CCW) is the integrated design environment software package that is used to program, design, and configure your Rockwell Automation Connected Components devices such as, Micro800 programmable logic controllers, PowerFlex drives, SMC soft-starters, and PanelView Component operator interface terminals.

This lab will demonstrate and help guide you on how to use and program a Micro850 controller using the CCW software.

## **Tools & prerequisites**

- Software: Connected Components Workbench Select Version “See Class Website for Version”
- Hardware: Micro850 Programmable Logic Controller, Catalog 2080-LC50-24QBB

## **Please note:**

CCW is an all-encompassing software package for component class controllers (or- small / micro controllers). It contains the application programming environment for the Micro800 Programmable Controllers (PLC), Drives (Variable Frequency Drives or VFD’s which use AC voltage, converted to DC, generate a Pulse Width Modulated (PWM) signal to control AC induction Motors) Human-Machine Interface (HMI) displays for control, feedback to an operators panel and some Safety PLC’s.

With that- all User Manuals are included in CCW as well as a very extensive Help menus.

At any time that you need help or reference to any item, component or object, simply click on the help pulldown

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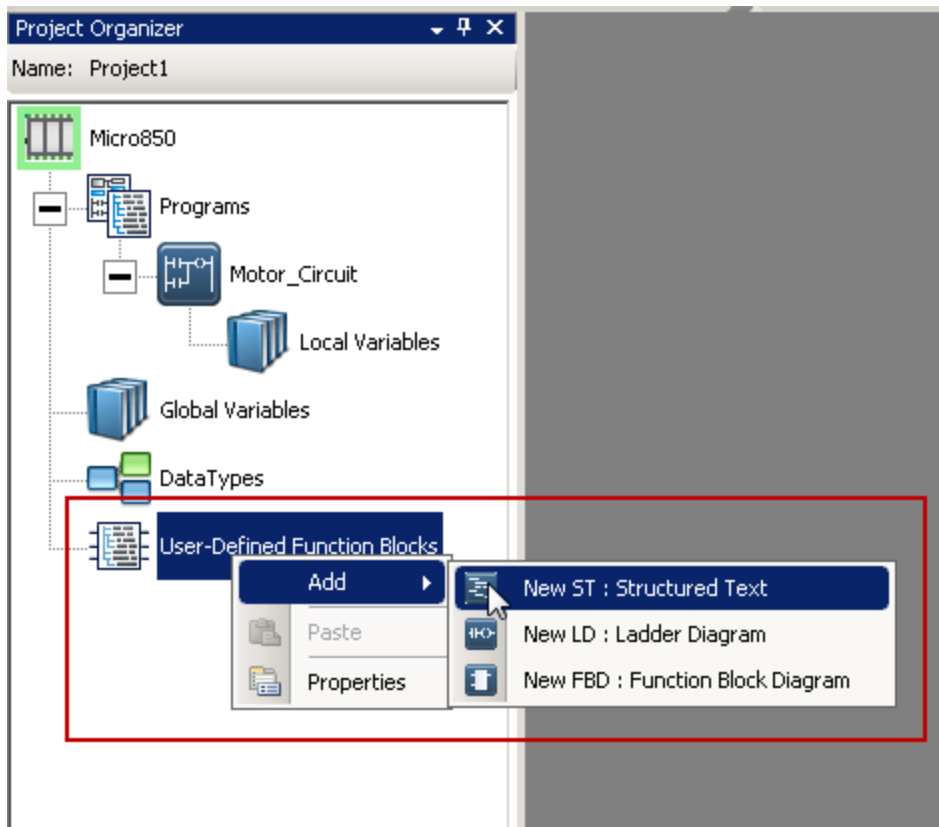
## Learn about User Defined Function Blocks

In this section of the lab, you will learn about a User Defined Function Block (UDFB), and how to create one using Structured Text.

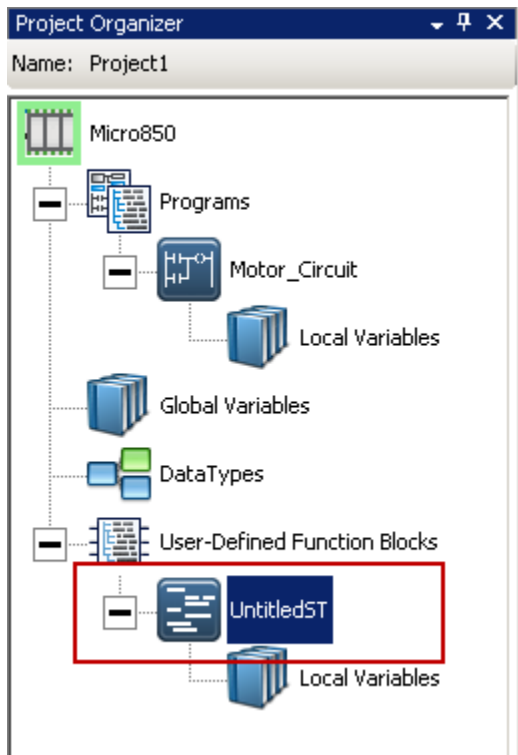
A User-Defined Function Block is a user defined program that can be packaged into an Instruction Block and reused within your Micro800 project. A UDFB can be written in Ladder, Function Block, or Structured Text.

You will be creating a UDFB to calculate the volume of a cylinder based on an inputted radius and height value.

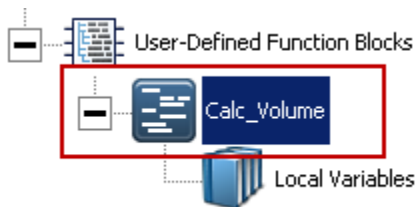
1. In your current project, right click **User-Defined Function Blocks** and select **Add → New ST: Structured Text**.



2. A program called **UntitledST** will be created under User-Defined Function Blocks.

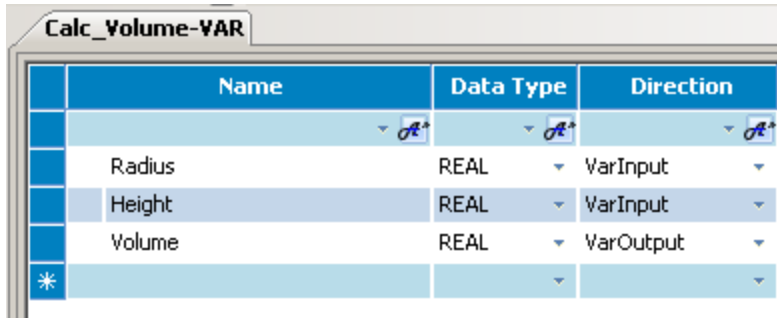


3. Rename this UDFB, **Calc\_Volume**.



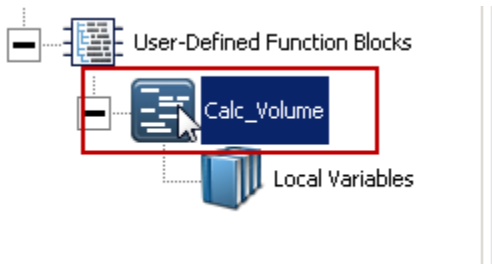
4. Double-click Local Variables under Calc\_Volume.

5. Create the following variables. Take careful note to properly configure the **Direction** property. This property defines whether the variable is an Input, Output, or standard Variable.



Name	Data Type	Direction
Radius	REAL	VarInput
Height	REAL	VarInput
Volume	REAL	VarOutput
*		

6. Next, double-click the **Calc\_Volume** UDFB to launch the program editor in the main project window.

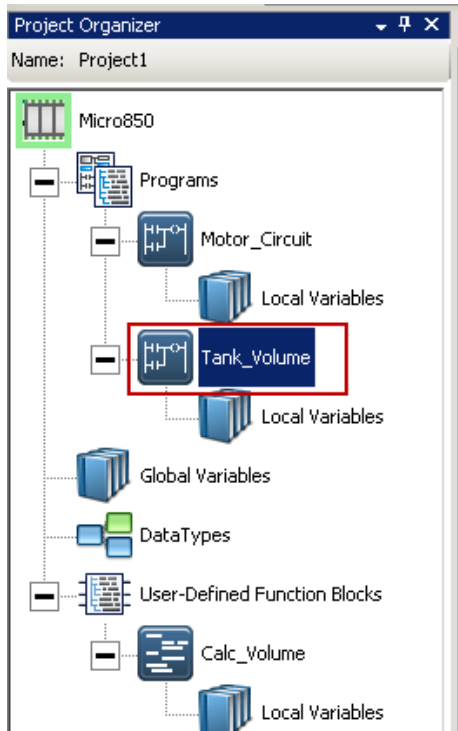


7. Add the following line of code to the program.

```
Volume := 3.14 * Radius * Radius * Height;
```

8. You have completed creating your UDFB.
9. Save your program.

10. Next, create a new ladder diagram program called **Tank\_Volume**.



11. Open the Local Variables for the Tank\_Volume program, and create the following variables. Notice the Data Type for the variable **Calc\_Tank\_Volume** is the Calc\_Volume UDFB you created.

Tank_Volume-VAR	
Name	Data Type
+	Calc_Tank_Volume
	Radius
	Height
	Volume
*	

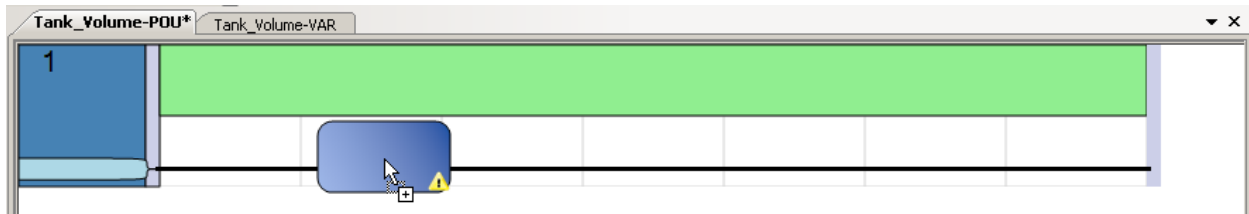
NOTE: Difference Between Real and Integer Values when declared or used to debug a program

Integer Value: is a whole number without a decimal place (I.E 2)

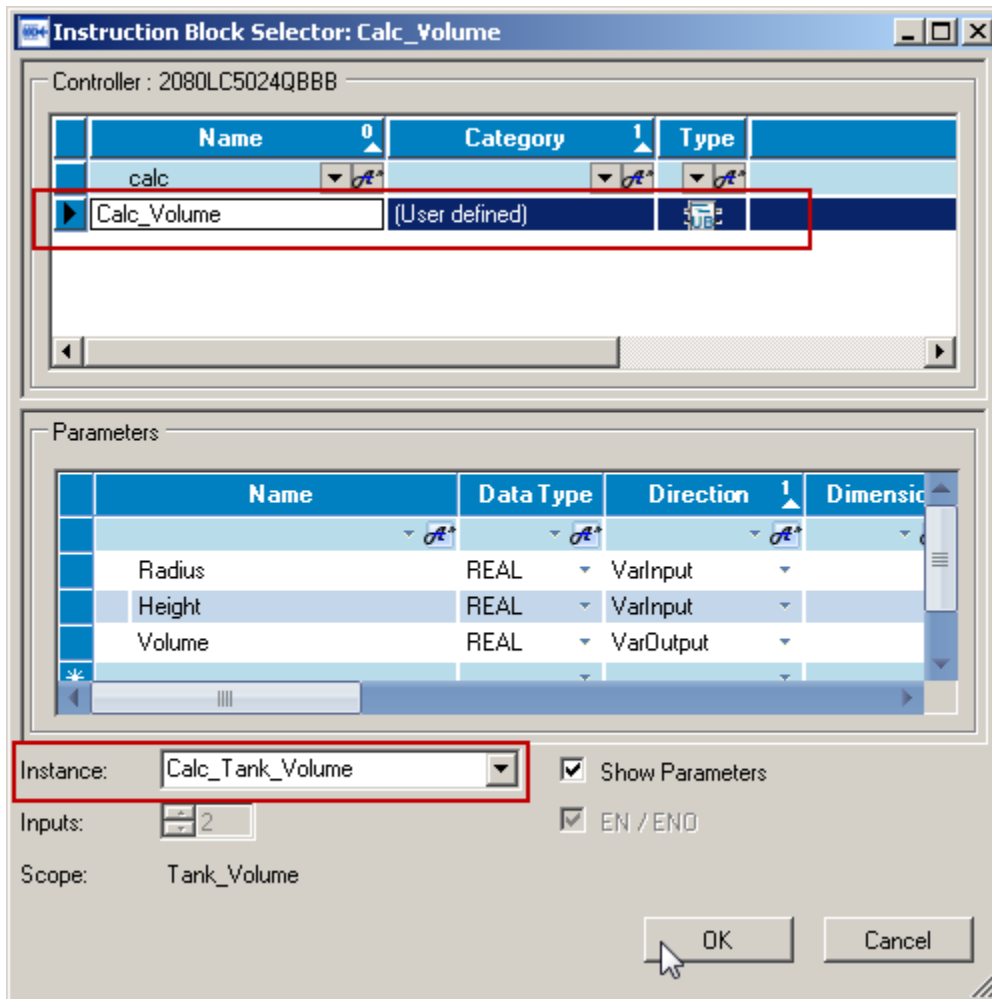
Real Value: is a number with a decimal place (I.E 2.0). It is important to add the decimal and at minimum one place past the decimal point (even it is a 0 value) or the software will give an error during the program build and will not execute the program.



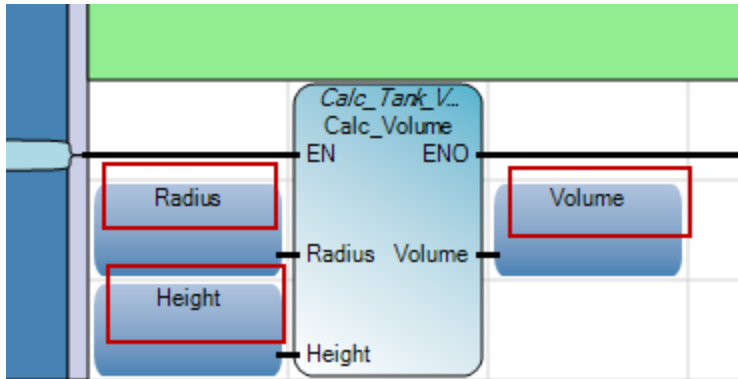
12. Next, open the **Tank\_Volume** program, and add a **Block** Instruction to the first rung.



13. Select the **Calc\_Volume** UDFB, and specify the Instance **Calc\_Tank\_Volume**. Then click **OK**.



14. Next, specify the following variables for each parameter of the Block.



15. Save your project.

16. Build and download your program to your Micro850 controller.

17. Once your download is complete, press the F5 key to enter Debug Mode.

18. Open the Local Variables of your Tank\_Volume program, and set the value of Radius to 5, and Height to 10.

The screenshot shows the 'Local Variables' window for the 'Tank\_Volume-POU' program. The window is divided into two tabs: 'Tank\_Volume-VAR' and 'Tank\_Volume-POU'. The 'Tank\_Volume-POU' tab is active. The window displays a table of local variables for the 'Calc Tank Volume' block. The variables are 'Radius', 'Height', and 'Volume'. The values are 5.0, 10.0, and 785.0 respectively. The 'Radius' and 'Height' rows are highlighted with a red box.

Name	Logical Value
+	...
Calc Tank Volume	...
Radius	5.0
Height	10.0
Volume	785.0

19. The value of Volume should read 785.0.

Name	Logical Value
+	...
Calc_Tank_Volume	...
▶ Radius	5.0
Height	10.0
Volume	785.0

20. Change the value of Radius to 7.0

Name	Logical Value
+	...
Calc_Tank_Volume	...
▶ Radius	7.0
Height	10.0
Volume	1538.6

21. The value of Volume should read 1538.6

Name	Logical Value
+	...
Calc_Tank_Volume	...
▶ Radius	7.0
Height	10.0
Volume	1538.6

22. Press Shift+F5 to exit Debug Mode.

23. You have completed this section of the lab.

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### Assignment 3: Warning Overflow

**Directions:** Complete after working on the tutorial pages 42-49. Create a program that will do the following

1. Storage container Cone: research the volume formula for a cone modify user defined function block
2. Cone Size: Radius 10"; Height: 5"
3. Program: Simulate the filling of the cone with material and showing a warning light if the fill is to high
  - a. Program Start with DI4 Direct Contact
  - b. Create a Function Block to calculate the volume of a defined cone above
  - c. Create a variable for Fill Test Values (These will be inputted manually to test the program)
    - i. 500 in<sup>3</sup>
    - ii. 100 in<sup>3</sup>
    - iii. 600 in<sup>3</sup>
4. Output:
  - a. If Fill Test Value is < 250 then both Green Lamps will turn ON
  - b. If Fill Test Value is 250 <= x <= 525 then One Green Lamp and One Yellow Lamp will turn ON
  - c. If Fill Test Value is > 525 then both Red Lamps will turn ON; wait 3 seconds and then turn OFF the Lights (this is to simulate the shutdown of the system because it is too full).

HINT: Use Instruction Block Comparison

NOTE: May use multiple rungs to figure this out.

#### Submission:

- A. Show/Video program working (Show computer screen and PLC Board)
- B. Printout a copy of the program